

# Endüstriyel Otomatik Kontrol Sistemleri

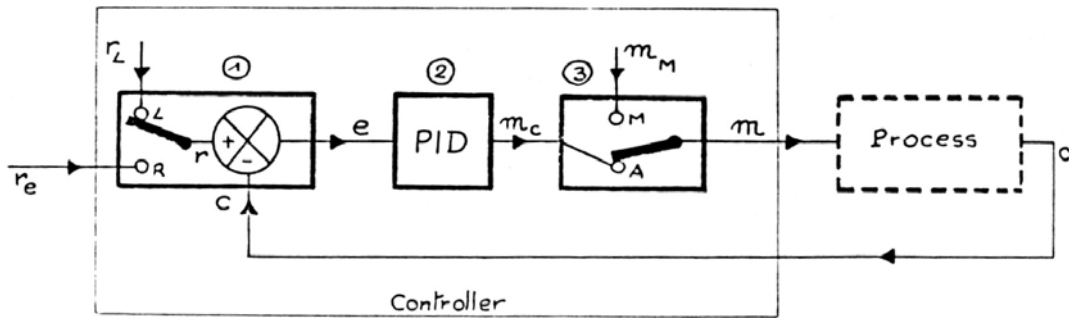
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## Dersin Konusu: Ayrık Devre Elemanlar ile Kontrol ve Uygulamaları

### Dersin Amacı:

Ayrık devre elemanları kullanılan endüstriyel otomatik kontrol sistemlerinin denetleyici özellikleri, iç donanımı ve elektronik devrelerinin incelenmesi, uygulama devrelerinin analizi, incelenmesi ve tasarlanmasının öğretilmesidir.

## Elektronik Denetleyicilerin özellikleri, iç devreleri



$r$  : referans girişi (set-point)

$r_L$  : iç referans girişi

$r_e$  : dış referans girişi

$e$  : hata işareti

$m$  : denetlenen değişken (denetleyicinin çıkış işareti)

$m_M$ : elle belirlenen çıkış işareti

$m_C$  : hesaplanmış çıkış işareti

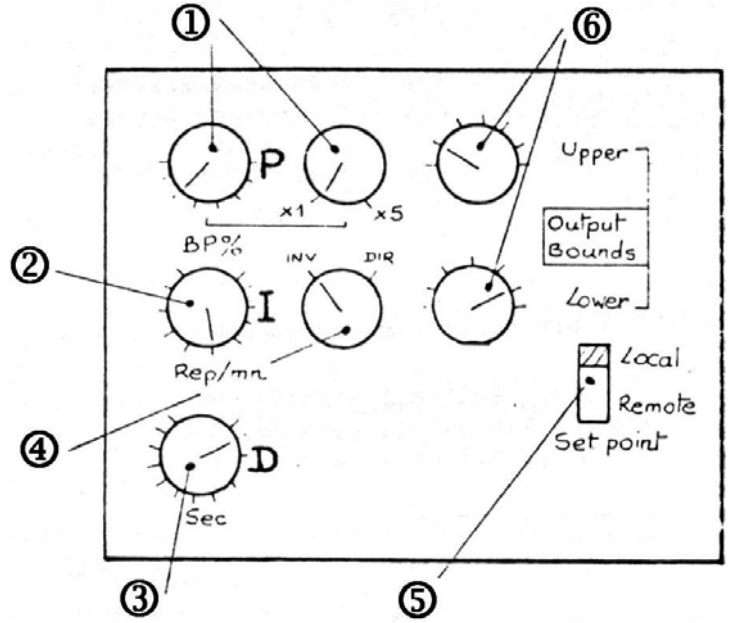
$c$  : denetlenen sürecin değişkeni (denetleyicinin giriş işareti)

## Bir PID denetleyicinin ayarları

- 1) Oransal kontrol ayarı, P
- 2) Entegral kontrol ayarı, I
- 3) Türev kontrol ayarı, D
- 4) Normal/Ters anahtarı
- 5) İç/Dış anahtarı
- 6) Kontrol edilen değişkenin alt ve üst sınır ayarları

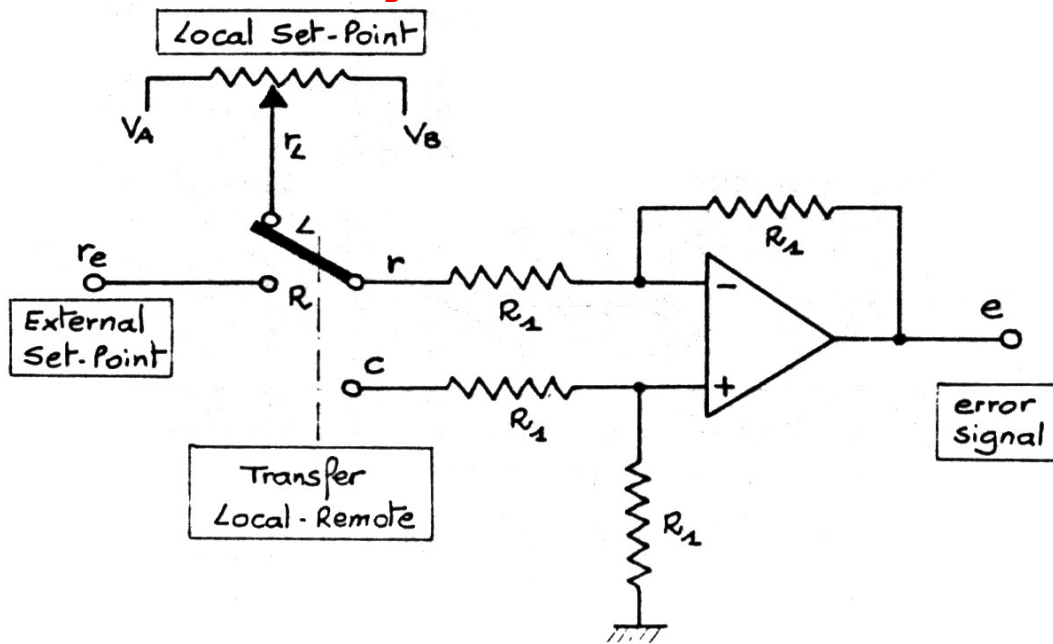
$$K \left[ 1 + \frac{1}{sT_I} \right] \left[ 1 + sT_D \right]$$

$$K \left[ 1 + \frac{1}{sT_I} + sT_D \right]$$



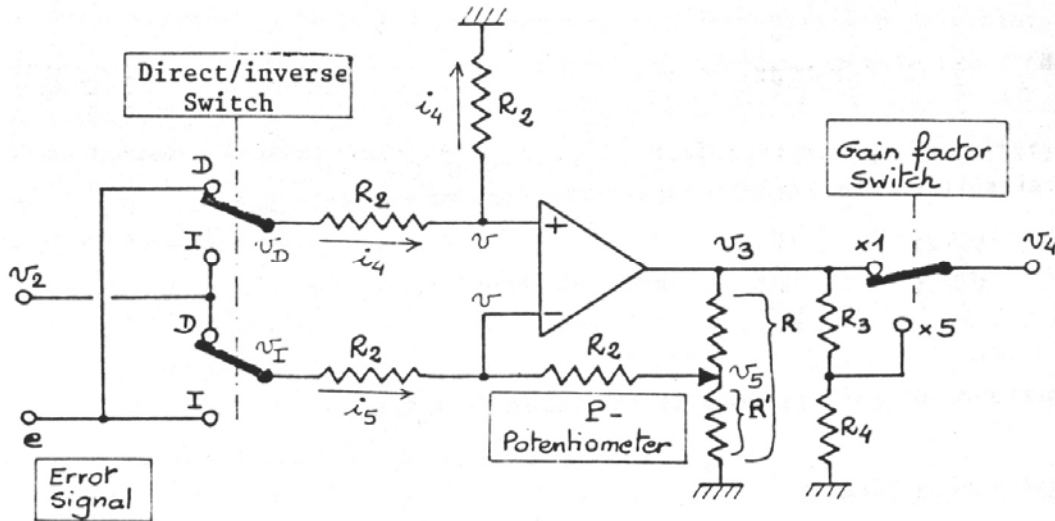
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## Giriş kontrol devresi



$$e = c - r$$

## Oran kontrol devresi

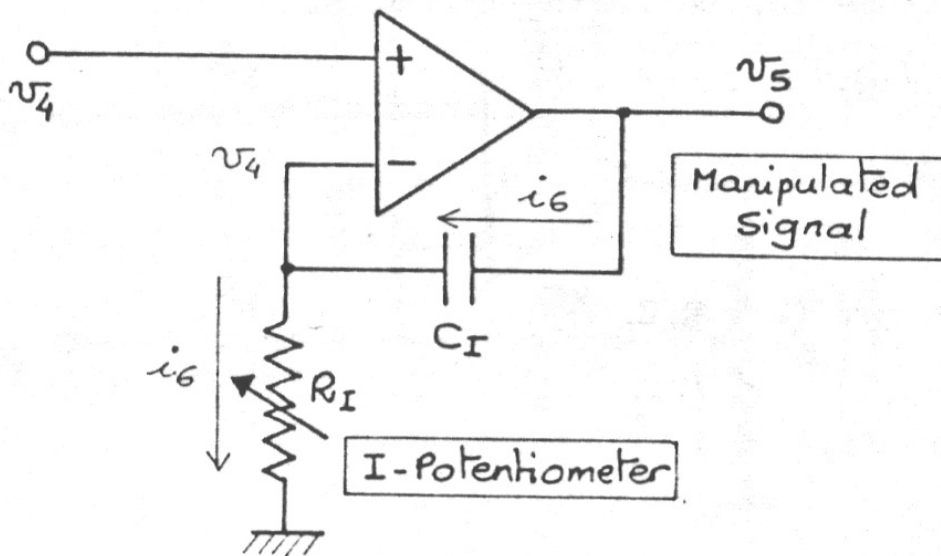


$$V_3 = K (V_e - V_2)$$

$$V_3 = (R/R') (V_e - V_2)$$

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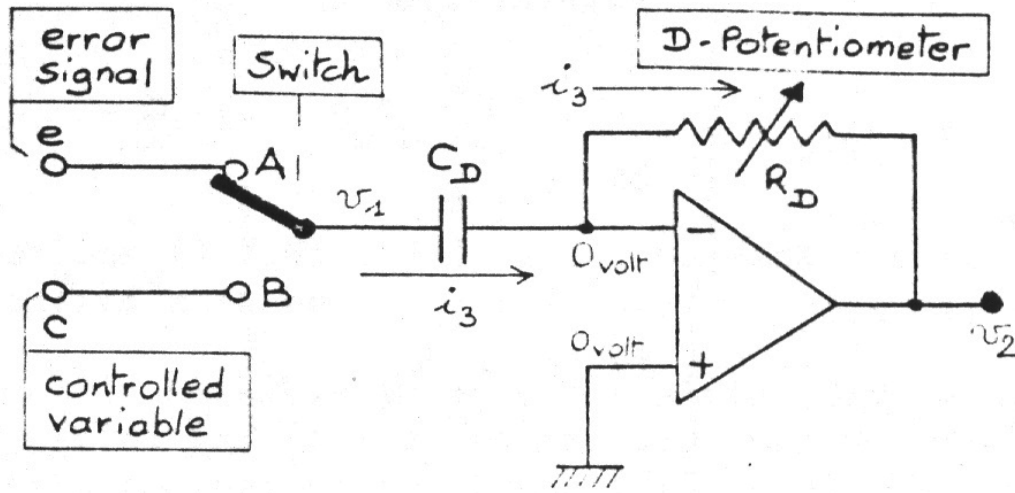
## Entegral kontrol devresi



$$V_5(s) = \left[ 1 + \frac{1}{R_I C_I s} \right] V_4(s)$$

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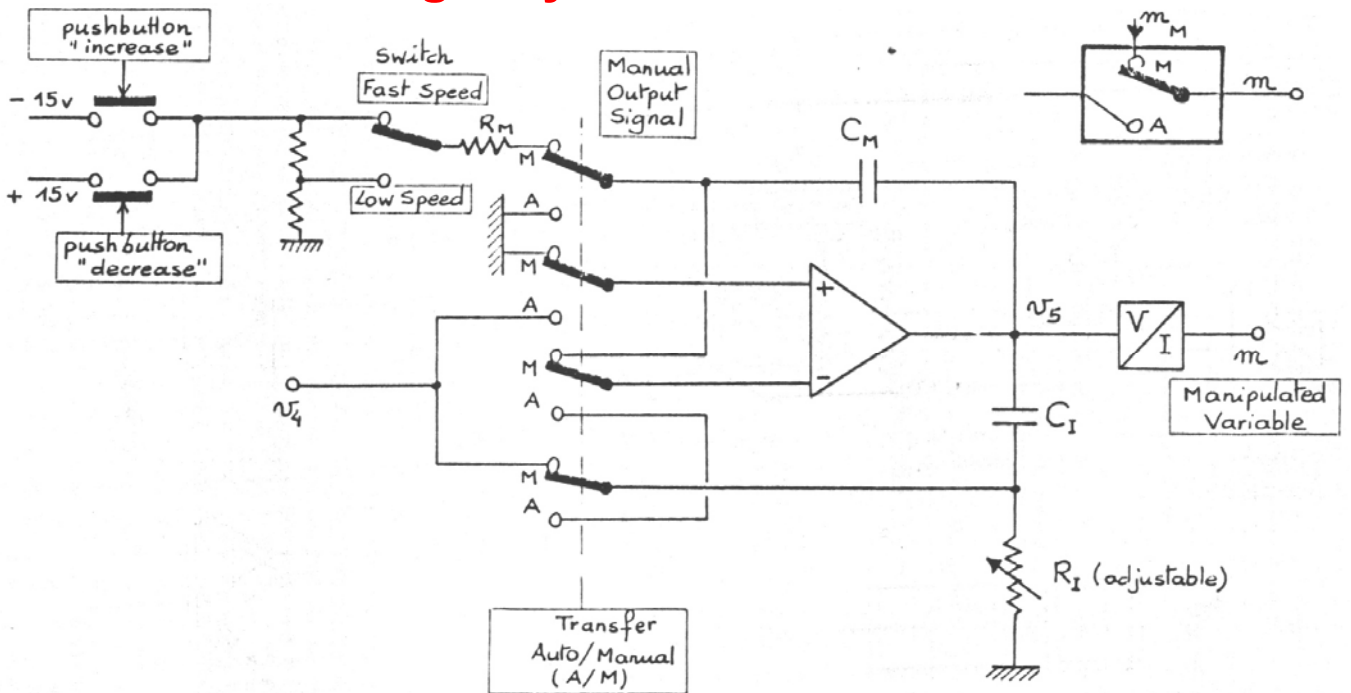
## Türev kontrol devresi



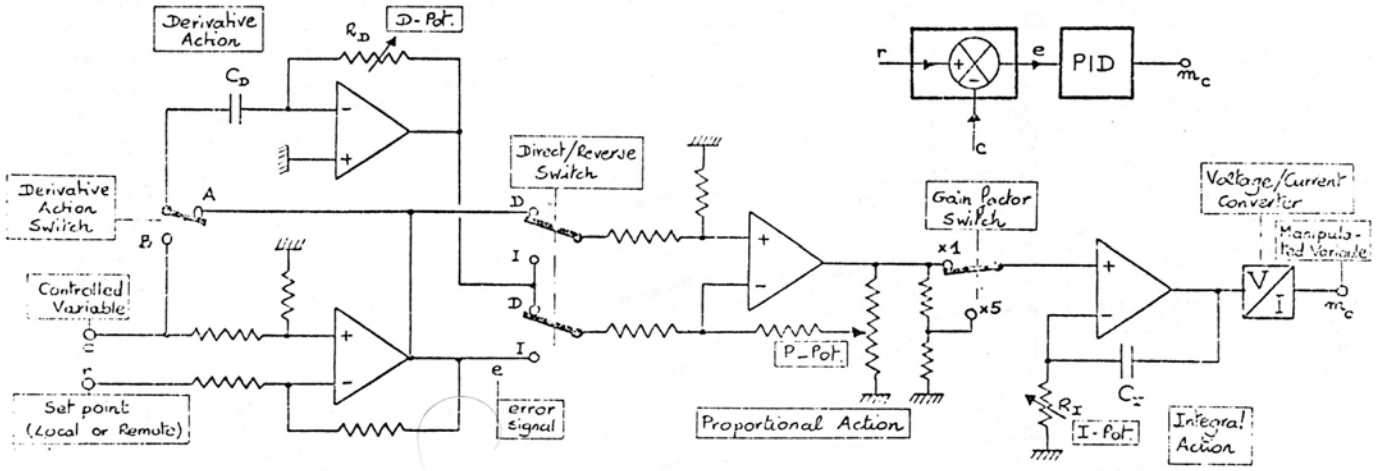
$$V_2(s) = -R_D C_D s V_1(s)$$

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## Diğer ayarların devresi



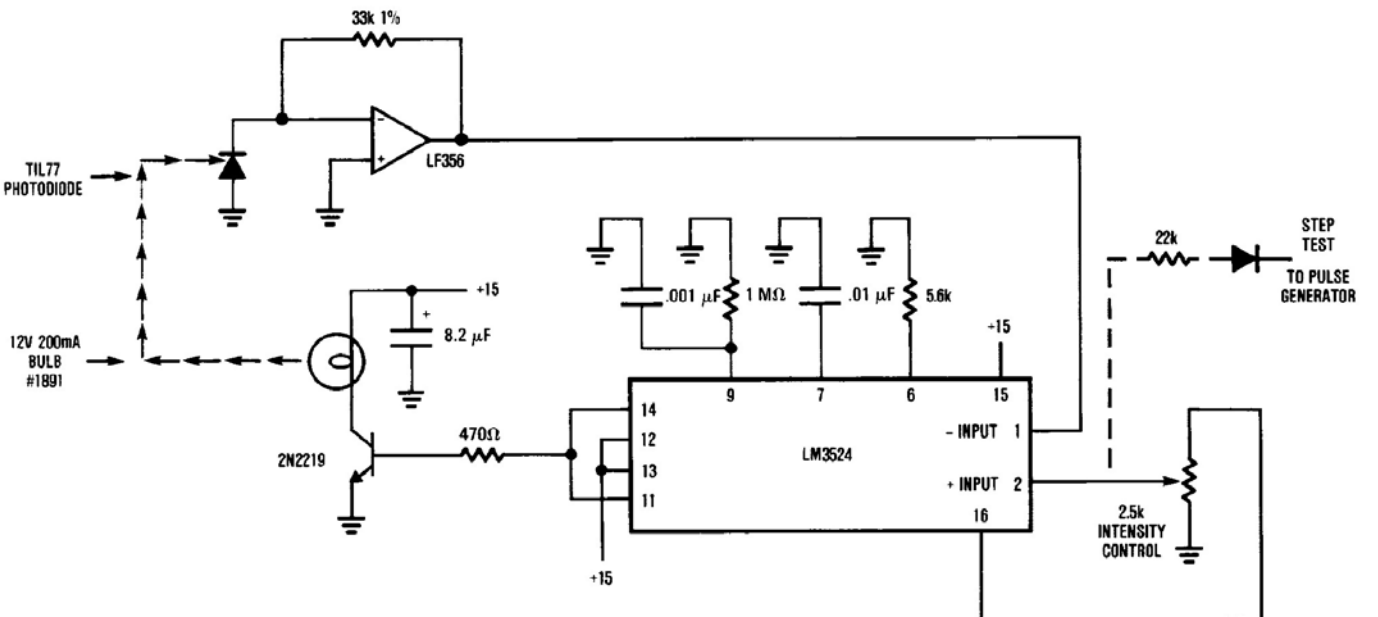
## PID kontrol devresi



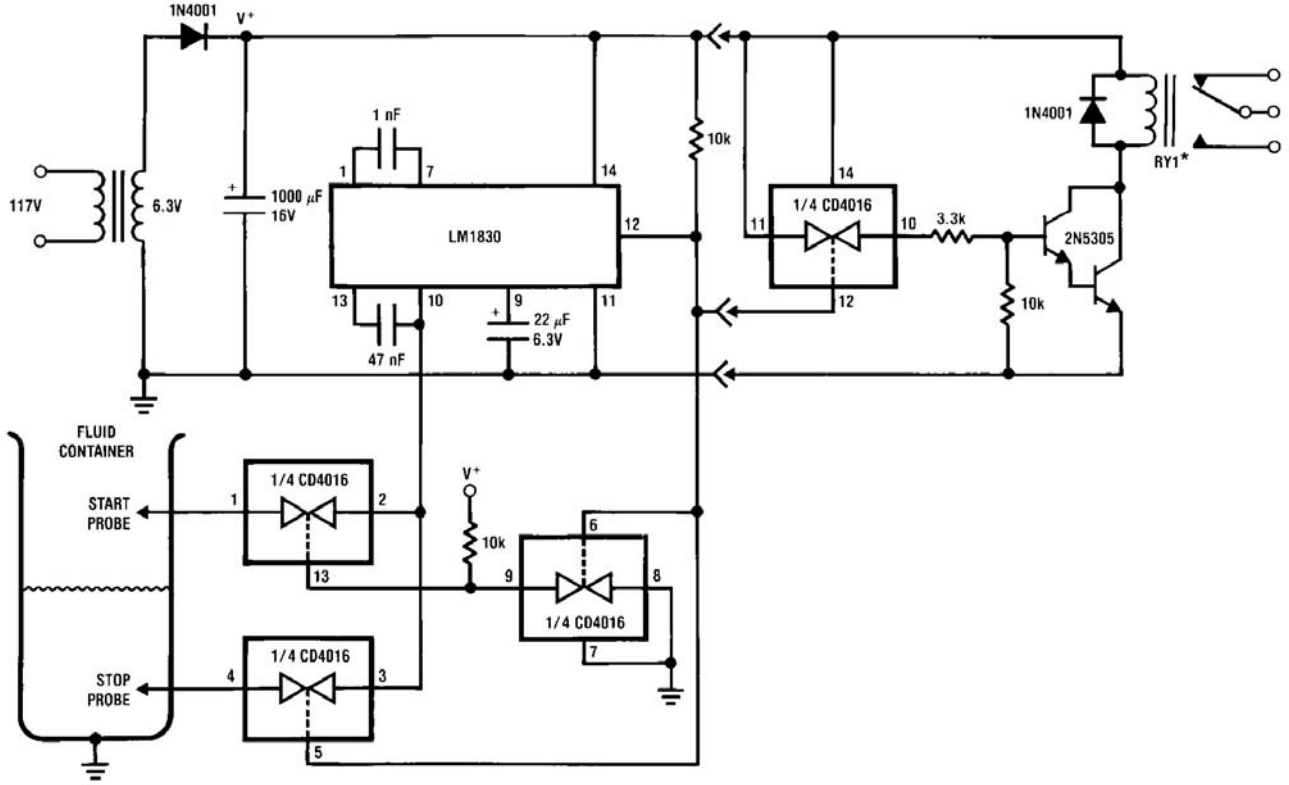
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## Ayrık devre elemanları kullanılan kontrol Uygulamaları

### Parlaklık kontrol devresi

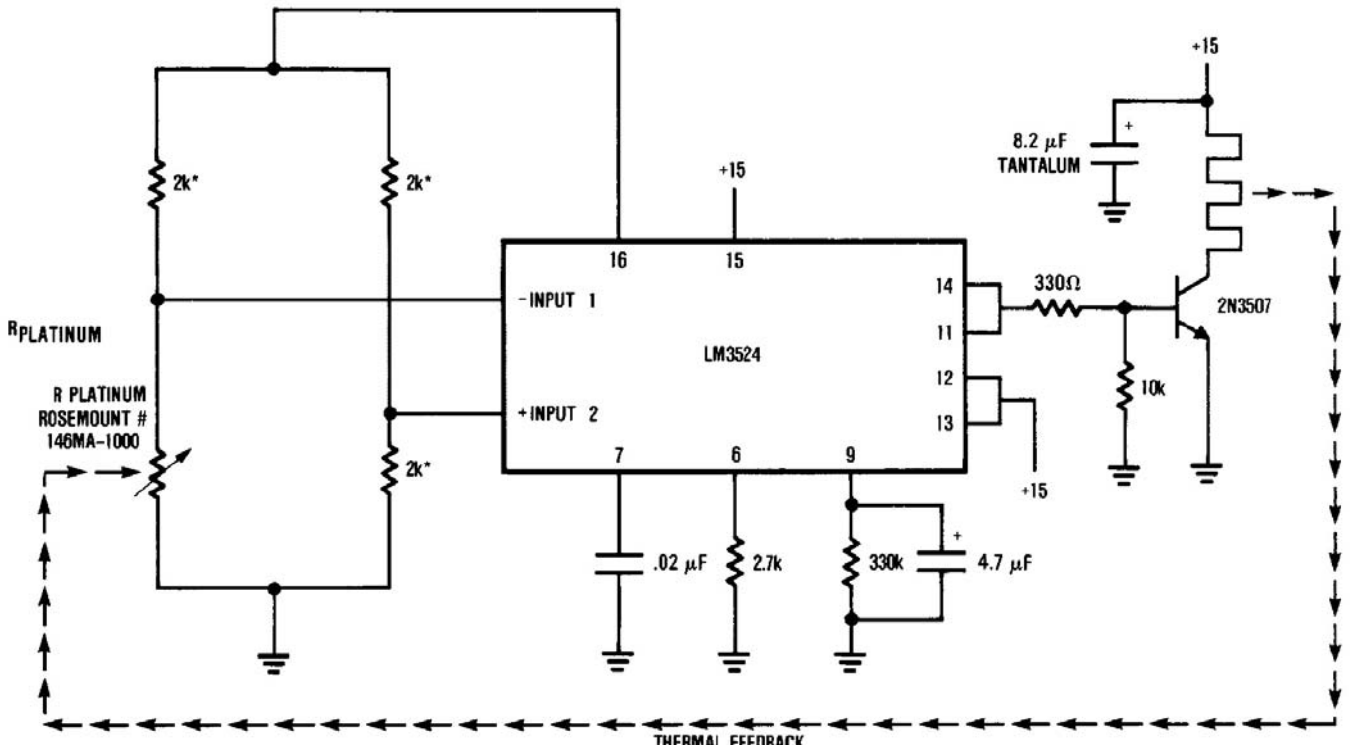


## Sıvı seviye kontrol sistemi

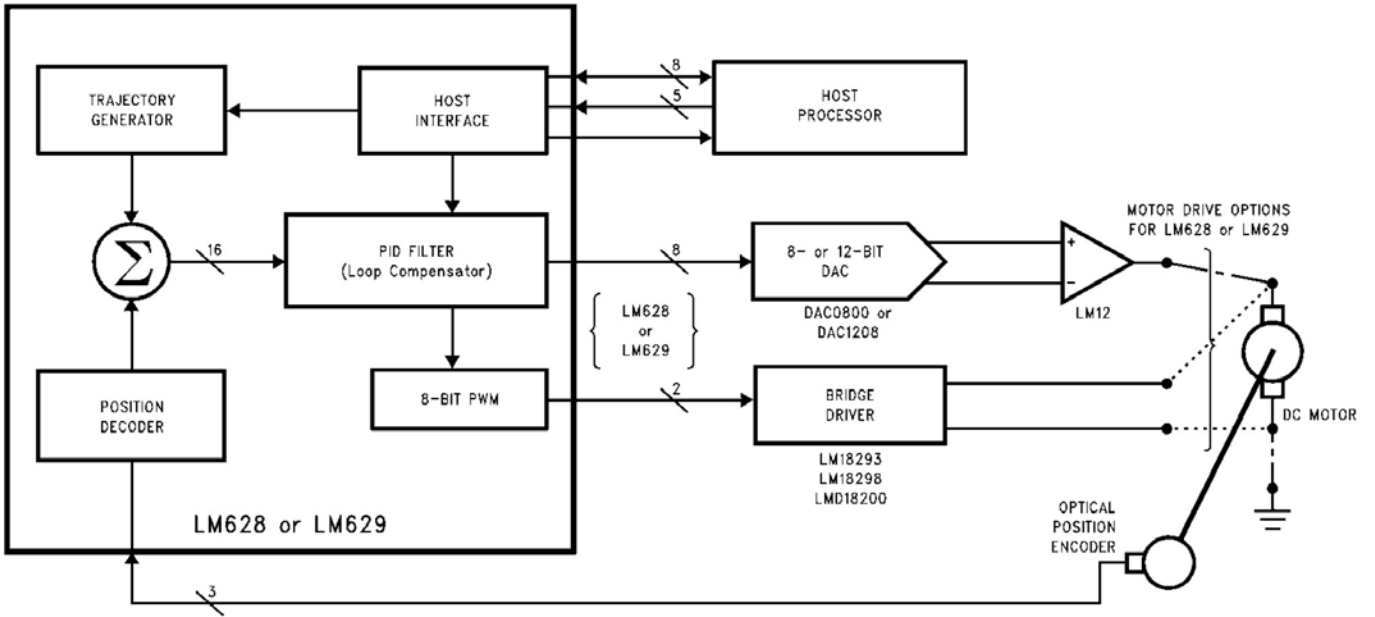


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## Sıcaklık kontrol sistemi

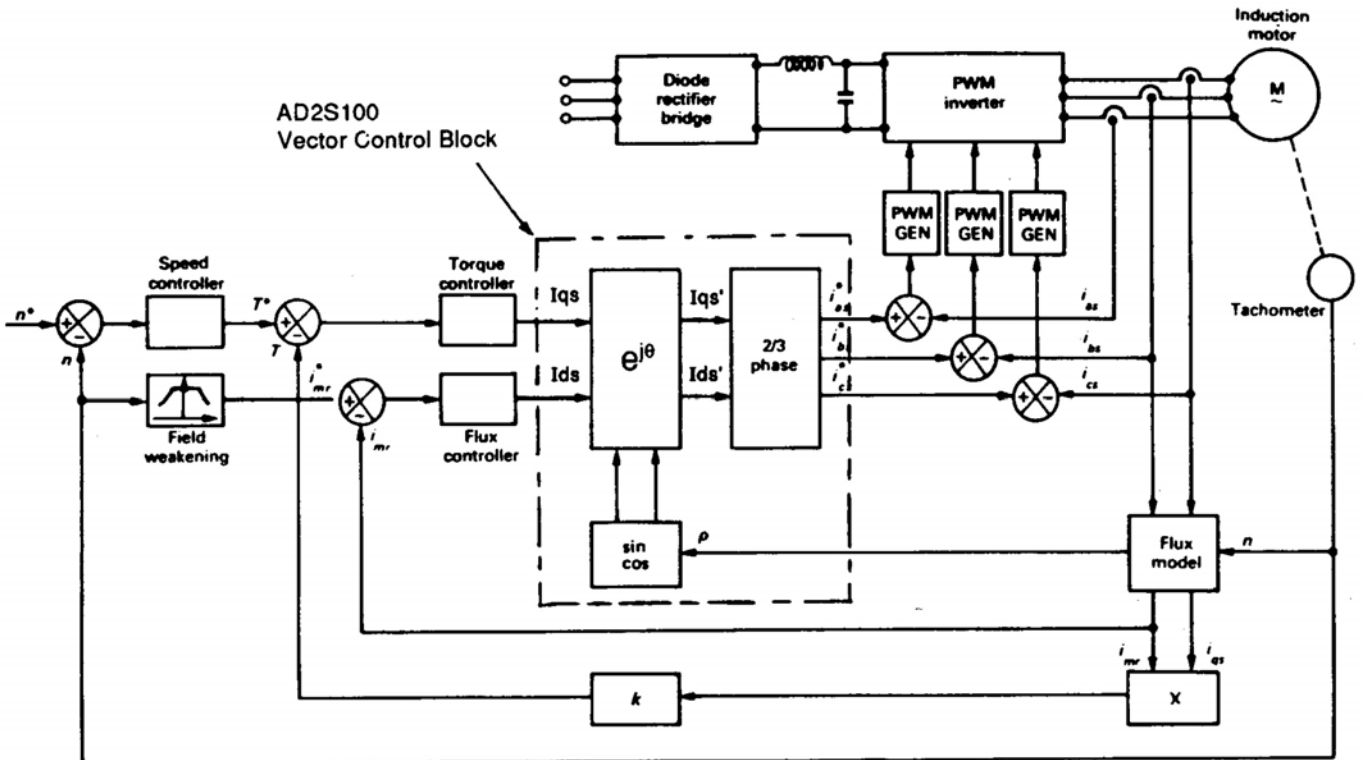


## Konum kontrol sistemi



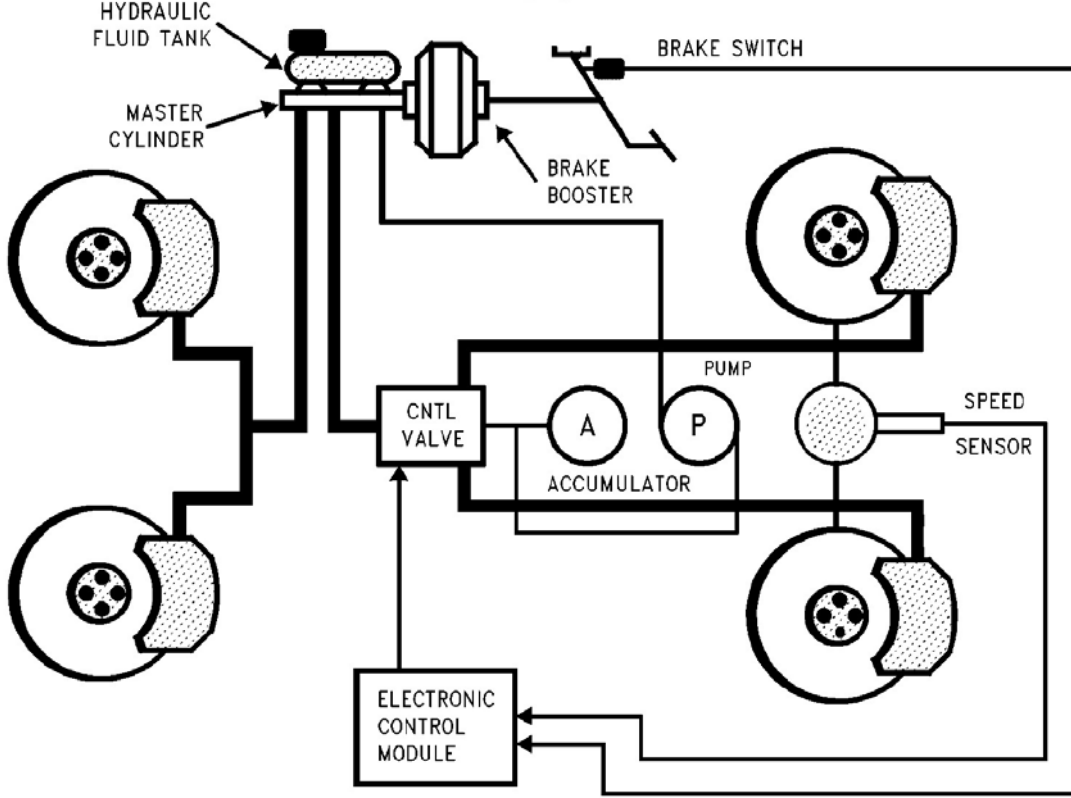
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## AC motor vektör kontrol sistemi



## Fren kontrol sistemi

### Anti-Lock Braking System/1 Channel



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## KAYNAKLAR

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